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(71) Applicant (for all designated States except US): DURAN B.V. [NL/NL], Koxkampseweg 10, NL-5301 KK Zaltbommel

(72) Inventor; and

- (75) Inventor/Applicant (for US only): DE VRIES, Gerard, Hendrik, Joseph [NL/NL]; Oeverzwaluw 23, NL-5221 GM s'-Hertogenbosch (NL).
- (74) Agent: DE BRUUN, Leendert, C.; Nederlandsch Octrooibureau, Scheveningseweg 82, P.O. Box 29720, NL-2502 LS The Hague (NL).

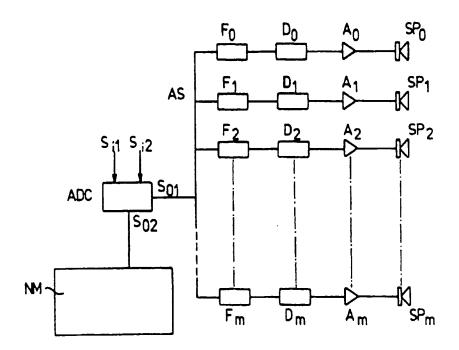
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(54) Title: LOUDSPEAKER SYSTEM WITH CONTROLLED DIRECTIONAL SENSITIVITY



#### (57) Abstract

Loudspeaker system having various loudspeakers (SPi, i = 0, 1, 2, ..., m) which are arranged in accordance with a predetermined pattern and have associated filters (Fi, i = 0, 1, 2, ..., m), which filters all receive an audio signal (AS) and are equipped to transmit output signals to the respective loudspeakers (SPi) such that they, during operation, generate a sound pattern of a predetermined form, wherein the loudspeakers (SPi) have a mutual spacing (li), which, insofar as physically possible, substantially corresponds to a logarithmic distribution, wherein the minimum spacing is determined by the physical dimensions of the loudspeakers used.

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Loudspeaker system with controlled directional sensitivity

The invention relates to a loudspeaker system comprising various loudspeakers which are arranged in accordance with a 5 predetermined pattern and have associated filters, which filters all receive an audio signal and are equipped to transmit output signals to the respective loudspeakers such that they, during operation, generate a sound pattern of a predetermined form.

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A loudspeaker system of this type is disclosed in US Patent 5 233 664. The system described in said patent comprises m microphones, which arranged are N loudspeakers and predetermined distances away from the loudspeakers. Each loudspeaker receives an input signal from a separate series 15 circuit of a digital filter and an amplifier. Each of said series circuits receives the same electrical input signal, which has to be converted into an acoustic signal. The digital filters have filter coefficients which are adjusted by a control unit, which receives, inter alia, output signals from arranged The loudspeakers are microphones. 20 the predetermined manner. The objective is to be able to generate a predetermined acoustic pattern. During operation the control unit receives the output signals from the microphones and, on the basis of these, adjusts the filter coefficients of the 25 digital filters until the predetermined acoustic pattern has been obtained. Loudspeakers in a linear array, in a matrix form and in a honeycomb structure are described in the embodiments.

The directional sensitivity of the known loudspeaker system can be controlled up to about 1400 Hz for the embodiments with 30 a linear array and a matrix arrangement. An upper limit of about 1800 Hz is cited for the honeycomb structure. This upper limit is inadequate for many audio applications and it would be desirable to provide a loudspeaker system which can control the directional sensitivity up to frequencies of about 10 kHz.

In J. van der Werff, "Design and Implementation of a Sound 35 Column with Exceptional Properties", 96th Convention of the AES (Audio Engineering Society), February 26 - March 1, 1994, Amsterdam, an analogue loudspeaker system is described in which

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the individual loudspeakers are arranged at non-equidistant spacings along a straight line. The gaps between the individual loudspeakers are calculated on the basis of the criterion of maintaining the side lobes of the acoustic pattern transmitted during operation so as to be at a suitably low level. The density of the number of loudspeakers per unit length is greater in the vicinity of the acoustic centre than at a distance away from this.

The primary objective of the present invention is to provide a loudspeaker system which has a controlled directional sensitivity over as wide a frequency range as possible.

A further objective of the invention is to provide a loudspeaker system wherein the maximum deviation of the directional sensitivity is as far as possible constant over the envisaged frequency range.

To this end, the invention provides a loudspeaker system according to the type described above, characterised in that the loudspeakers have a mutual spacing, which, insofar as physically possible, substantially corresponds to a logarithmic distribution, wherein the minimum spacing is determined by the physical dimensions of the loudspeakers used. By not making the mutual spacing of the loudspeakers equidistant but adapting it to the frequency requirements, it is possible to control the directional sensitivity up to, certainly, 8 kHz. The side lobe level is reduced at the same time. By choosing a logarithmic distribution, the maximum deviation of the directional sensitivity over the envisaged frequency range is kept as constant as possible and spatial aliasing at higher frequencies is counteracted. Primarily it is not so much the form of the sound pattern as the transmission angle which is controlled.

There are various possibilities for the arrangements. For instance, the loudspeakers can be arranged along a straight line, in which case the said distribution extends from a central loudspeaker in one direction along said line.

As an alternative, the loudspeakers can be arranged along two straight line sections, in which case the said distribution extends from a central loudspeaker in two directions along the two line sections, which central loudspeaker is located at an

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intersection of the two line sections.

The two line sections can be on a straight line.

As a further alternative, the loudspeakers can be arranged on two lines which cross one another or can be arranged in the form of a matrix.

Preferably, the loudspeakers are identical.

The loudspeakers can be arranged in various rows, each of which is optimised for a specific, predetermined frequency band. The loudspeakers arranged in said rows can, for example, be of different dimensions and/or have a different logarithmic distribution.

The filters can be FIR filters or IIR filters.

Preferably, the filters are digital filters which have predetermined filter coefficients and are each connected in series with associated delay units having predetermined delay times, which filter coefficients and delay times are stored in a memory, for example an EPROM.

The audio signal preferably originates from an analogue/digital converter, which also has an input for receiving a background signal corresponding to the sound in the surroundings. Said analogue/digital converter can be provided with an output for connection to at least one dependent ancillary module.

The invention will be explained in more detail below with 25 reference to a few diagrammatic drawings, in which:

Figure la shows an effective, normalised array length as a function of the angular frequency for a distribution of three loudspeakers per octave band;

Figure 1b shows the deviation of the opening angle  $\alpha$  as a 30 function of the angular frequency for a distribution of three loudspeakers per octave band;

Figures 2a to 2d show various arrangements of loudspeakers in accordance with the present invention;

Figure 3 shows a diagrammatic overview of an electronic 35 circuit which can be used to control the loudspeakers; and

Figure 4 shows an example of an acoustic pattern.

The present description refers to an array of loudspeakers. Such an array can be one-dimensional (line array) or two-

dimensional (plane).

If the transmitting portion for each frequency component in a sound signal which is reproduced is proportional to the wavelength of the frequency component concerned, the array is 5 found to display frequency-independent behaviour. Two concepts are important for good understanding of the present invention: the opening angle and the transmission angle. The opening angle is, by definition, the angle through which a sound source can be turned such that the sound pressure does not fall by more 10 than 6 dB with respect to the maximum value which is measured at a fixed point in a plane in which the sound source is located, and at a distance which is large compared with the physical dimensions of said sound source. Said angle is indicated by "a" in Figure 4, which figure will be discussed 15 further below. The transmission angle is, by definition, the angle B which the axis of symmetry of the transmission pattern makes with a plane perpendicular to the axis along which a onedimensional array is arranged, or with a middle vertical line of the plane in which a two-dimensional array is arranged 20 (Figure 4). In the case where a two-dimensional array is used, two opening angles and two transmission angles can be defined for a transmission pattern.

The following relationship applies for the dimensions of the effective portion of a linear array having an infinite 25 number of loudspeakers, as a function of the frequency:

$$I(\omega) = k \cdot \lambda = \frac{c_0 \cdot 2 \cdot \pi}{\omega} \tag{1}$$

where:  $l(\omega)$  = the effective array size,

 $C_0$  = the speed of sound (m/s)

k = a proportionality constant, which is a measure of the opening angle  $\alpha$ 

30  $\omega$  = angular frequency (rad/s)

The following rule of thumb can be used to calculate the proportionality constant k:

$$k = \frac{72^{\circ}}{\alpha} \tag{2}$$

where: a is the desired opening angle in degrees.

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This relationship for the proportionality constant k has an accuracy of more than 90 % for k > 1.

Because an array in practice does not consist of an infinite number of loudspeakers but is composed of a limited 1 number of loudspeakers, the array size  $l(\omega)$  is quantised. As can be seen from Figures 1a and 1b, this results in a limited resolution in the opening angle  $\alpha$ . Figure 1a shows the effective array length (logarithmic) as a function of the angular frequency (logarithmic 1/3 octave) for a distribution of three loudspeakers per octave band. Figure 1b shows the deviation of the opening angle  $\alpha$  as a function of the angular frequency for a distribution of three loudspeakers per octave band. Of course, this is merely an example and the invention is not restricted to three loudspeakers per octave band.

15 The criterion taken for calculation of the spacing of loudspeakers is that the maximum deviation of the directional sensitivity must be kept as constant as possible over the envisaged frequency range. As will become apparent below, this can be achieved by providing the loudspeakers used, SP<sub>1</sub>, SP<sub>2</sub>, ..., with a logarithmic arrangement with respect to a central loudspeaker SP<sub>0</sub>. This also results in minimalisation of the deviation of the opening angle α and minimalisation of the number of loudspeakers required.

The frequency-dependent variation in  $\alpha$  is inversely proportional to the number of loudspeakers per octave band and theoretically is 50 % for a distribution of one loudspeaker per octave. Preferably, in practice use is made of at least two to three loudspeakers per octave.

If the array size  $l(\omega)$  in a single dimension is quantised 30 with the aid of n steps per octave band, the following relationship then applies for the array size:

$$l(i) = k. \frac{C_0.2.\pi}{\omega_{\min}.2^{\frac{i}{2}}} \quad \text{where } 0 \le i \le n_{\max} - 1$$
 (3)

where:  $\omega_{\min}$  = the lowest reproducible angular frequency (radians per second) at which the opening angle  $\alpha$  is still controlled;

n = number of loudspeakers per octave band;

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the total number of discrete steps in a single dimension, depending on the desired frequency range.

For a value of i = 0, this gives the maximum physical 5 dimension of the array, which is dependent on  $\omega_{\min}$  and  $k(\alpha)$ .

The loudspeaker positions depend on the physical configuration of the array. Said configuration can be asymmetrical or symmetrical. In the case of an asymmetrical configuration, the central loudspeaker SP, is located at one 10 side of the array, as is shown in Figure 2a. The above Equation 3 applies for the distance l(i) between the loudspeaker positions and the central loudspeaker SPo, which corresponds to a logarithmic distribution. In order to produce such an array, n\_ loudspeakers are required in one dimension.

Figure 2b shows a symmetrical arrangement of loudspeakers 15 around a central loudspeaker SPo, which is located in the middle. The above Equation 3 multiplied by a factor of 1/2 applies for loudspeakers SP<sub>1</sub>, SP<sub>2</sub>, SP<sub>3</sub>, ..., whilst Equation 3 multiplied by a factor of -1/2 applies for loudspeakers ...

20 SP\_3, SP\_2, SP\_1. For a symmetrical arrangement according to Figure 2b, 2.n -1 loudspeakers are needed. It is found that the symmetrical arrangement according to Figure 2b gives a better suppression of the side lobe level than does the asymmetrical arrangement according to Figure 2a.

In fact, Figure 2b is a combination of 2 array configurations according to Figure 2a with coincident central loudspeakers. These two separate loudspeaker arrays can also be located on two line sections, which do not lie in the extension of one another.

Instead of the configurations shown in Figures 2a and 2b, two-dimensional configurations are also possible. Figure 2c shows a matrix arrangement of loudspeakers, in which various loudspeaker arrays according to Figure 2b are arranged parallel to one another.  $n_{\mbox{\tiny max hor}}$  .  $n_{\mbox{\tiny max vert}}$  loudspeakers are present in an 35 arrangement of this type. Here near hor is the number of loudspeakers in the horizontal direction and n ax vert is the number of loudspeakers in the vertical direction.

Figure 2d shows a two-dimensional configuration with an

arrangement in the form of a cross. Figure 2d shows two loudspeaker arrays according to Figure 2b which are arranged perpendicular to one another with a coincident central loudspeaker SP<sub>0.0</sub>. n<sub>bar ber</sub> + n<sub>bar vert</sub> -1 loudspeakers are present in the arrangement according to Figure 2.

Of course, arrangements along other and more lines crossing one another are also possible. The only proviso in the context of the present invention is that the various loudspeakers  $SP_{i,j}$  are arranged in accordance with a logarithmic distribution, for example as defined by the above Equation 3.

In practice, the loudspeakers have a definitive physical size. This physical size determines the minimal possible spacing between the loudspeakers. Those loudspeakers which, in accordance with the above Equation 3, would have to be placed 15 a distance apart which is smaller than the physical size permits are, in practice, placed in contact with one another. This leads to concessions with regard to the resolution in the frequency range concerned. Naturally, the concessions with regard to the resolution are as small as possible if the sizes 20 of the loudspeakers are chosen to be as small as possible. smaller loudspeakers usually have characteristics with regard to power and efficiency. Therefore, in practice, a compromise will always have to be made between the quality of the loudspeakers and the concessions in respect 25 of the resolution.

preferably, all loudspeakers must have the same transfer function. Therefore, all loudspeakers in the one-dimensional or two-dimensional array are preferably identical to one another.

It is, however, also possible to use various arrays arranged alongside one another which are provided with different loudspeakers, in which case the dimensions of the loudspeakers and their mutual positions in the various arrays are optimised for a specific limited frequency band. In that case no concessions have to be made in respect of the resolution and the power or the efficiency. Of course, this is at the expense of the number of loudspeakers required.

Figure 3 shows a diagrammatic overview of a possible electrical circuit for controlling the loudspeakers. For ease,

only the loudspeakers SPo, SP, ..., SP and the associated electronics are indicated in the figure. Therefore, Figure 3 corresponds to the loudspeaker array according to Figure 2a. However, similar electronic circuits also apply for other 5 loudspeaker arrays according to the invention, for example according to Figures 2b, 2c and 2d.

Each loudspeaker SP, receives an input signal from a series circuit comprising a filter  $F_i$ , a delay unit  $D_i$  and an amplifier  $A_i$ . The filters  $F_i$  are preferably digital filters of the FIR 10 (Finite Impulse Response) type or of the IIR (Infinite Impulse Response) type. If IIR filters are used, they preferably have a Bessel characteristic. The coefficients of the filters  $F_i$  are calculated beforehand and stored in a suitable memory, for This preferably takes place during example an EPROM. 15 manufacture of the loudspeaker system. The filter coefficients of the filters F; are then no longer adjusted during operation, so that it is then possible to dispense with an electronic control unit which would be connected to the filters F, and the delay unit D<sub>i</sub> for adjusting the filter coefficients, or the 20 delay times, during operation on the basis of the sound pattern recorded by microphones. However, use of such a feedback to a control unit (not shown here) and various microphones, as is disclosed in the abovementioned US Patent 5 233 664, is possible within the scope of the present invention.

The delay times for each of the delay units D, are preferably also calculated beforehand during manufacture and stored in a suitable chosen memory, for example in an EPROM. These delay times are then also no longer changed during operation.

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Each of the filters F, receives an audio signal AS via a first output So1 of an analogue/digital converter ADC. The analogue/digital converter ADC receives a first analogue input signal  $S_{i1}$ , which has to be converted by the loudspeakers  $SP_0$ , SP1, ..., into a sound pattern with a predatermined directional 35 sensitivity.

Preferably, the analogue/digital converter ADC is also connected to a measurement circuit which is not shown, which supplies a second input signal S12 which is a measure for the

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analogue/digital converter ADC and using the same sampling frequency for calculation of the filter coefficients as well. The delay units D<sub>i</sub> are fed at a sampling frequency of 96 kHz by doubling the first-mentioned sampling frequency. This gives a resolution of 10.4 microseconds. Of course, other sampling frequencies are also possible within the scope of the invention.

A loudspeaker array designed in accordance with the guidelines given above has a well defined directional sensitivity which is substantially frequency-independent over a wide frequency range, that is to say up to at least a value of 8 kHz. The directional sensitivity is found to be very good in practice.

It is also possible to design a loudspeaker array in 15 accordance with the guidelines given above with which the transmission pattern is not perpendicular to the axis along which the loudspeaker array is located (or the plane in which said array is located). The opening angle  $\alpha$  can be selected by making a suitable choice for the filter coefficients, whilst 20 any desired transmission angle  $\beta$  can be obtained by adjustment of the delay times. In this way, a sound pattern can be directed electronically. When a one-dimensional loudspeaker array is used, the transmission pattern is rotationally symmetrical with respect to the array axis 2. When a two-25 dimensional loudspeaker array is used, the transmission pattern is symmetrical according to a mirror image about the array plane. This symmetry can advantageously be used in situations in which the directional sensitivity of the sound which is generated at the rear of the loudspeaker array also has to be 30 controlled.

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Finally, Figure 4 shows an example of a (simulated) polar diagram to illustrate a possible result of a loudspeaker array designed according to the invention. The opening angle  $\alpha$  shown in this figure is approximately 10°, whilst the transmission angle  $\beta$  is approximately 30°. The arrangement of the loudspeaker array which generates the pattern shown is likewise shown diagrammatically. For the sake of convenience, the logarithmic distribution has been dispensed with in this

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diagram.

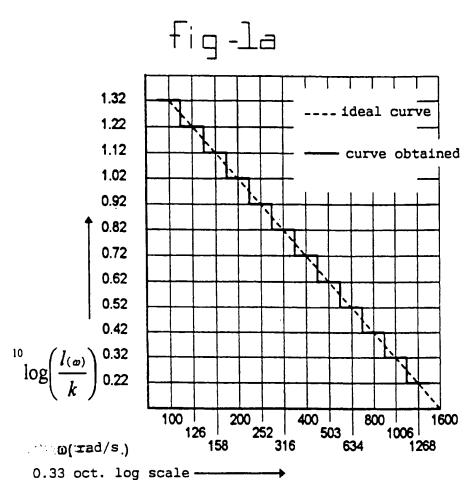
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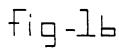
- 7. Loudspeaker system according to one of the preceding claims, characterised in that the loudspeakers  $(SP_i, SP_{i,j})$  are identical.
- 8. Loudspeaker system according to Claim 1, characterised in that the loudspeakers (SP<sub>i</sub>) are arranged in various rows, each of which has been optimised for a specific, predetermined frequency band.
- 9. Loudspeaker system according to one of the preceding claims, characterised in that the filters  $(F_i)$  are FIR filters or IIR filters.
- 10. Loudspeaker system according to one of the preceding claims, characterised in that the filters (F<sub>i</sub>) are digital filters which have predetermined filter coefficients and are each connected in series with associated delay units (D<sub>i</sub>) having predetermined delay times, which filter coefficients and delay times are stored in a memory, for example an EPROM.

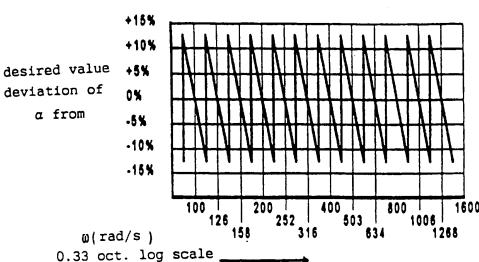
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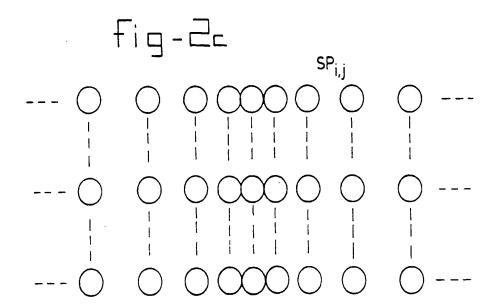
- 11. Loudspeaker system according to one of the preceding claims, characterised in that the audio signal (AS) originates from an analogue/digital converter (ADC), which also has an input for receiving a background signal (S<sub>12</sub>) corresponding to the sound in the surroundings.
- 12. Loudspeaker system according to Claim 11, characterised in that the analogue/digital converter (ADC) also has an output  $(S_{o2})$  for connection to at least one dependent ancillary module 30 (NM).

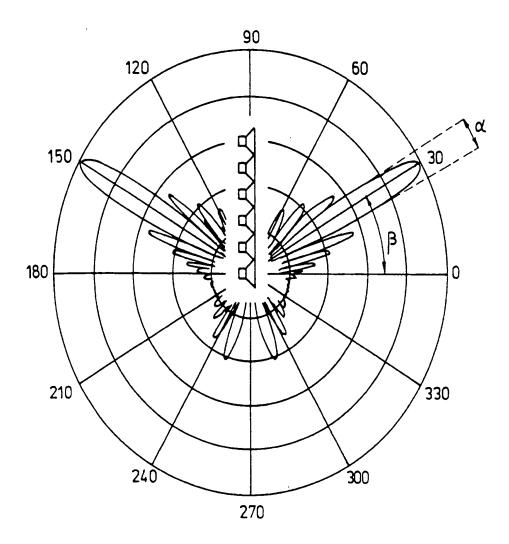
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